

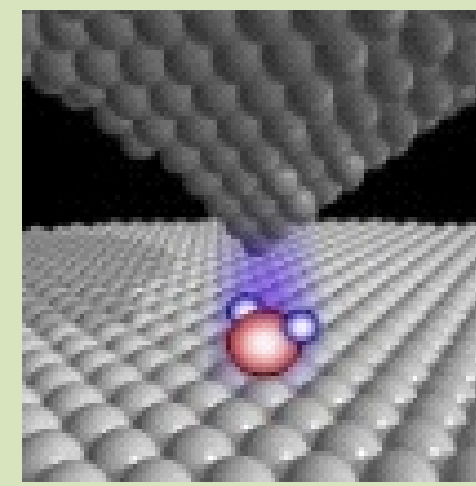
**PROGRAMUL OPERATIONAL SECTORIAL CRESTEREA COMPETITIVITATII ECONOMICE
AXA PRIORITARA 2 – COMPETITIVITATE PRIN CDI**

Operatiunea 2.1.2: Proiecte CD de înalt nivel stiintific la care vor participa specialisti din strainatate

PROIECT: Tehnologii SPFM în reactii ionice ale solutiilor reziduale în sol si realizarea de nanocompozite bazate pe nanotuburi de carbon pentru aplicatii de energie si mediu (SPFM-LA)

Study of the wetting properties of glycerol on solid substrates at the micro-scale

Antoniu MOLDOVAN, Petru–Marian BOTA, Iulian BOERASU, Matei BADEA, Dorel DOROBANTU
Dionezie BOJIN, Daniela BUZATU, Marius ENACHESCU
Center for Surface Science and NanoTechnology, University “Politehnica” of Bucharest



Abstract

A non-contact scanning probe technique – Scanning Polarization Force Microscopy (SPFM)– was successfully implemented for the study of the wetting properties of liquids on the surfaces of solid materials, at the micro- and nanoscale. SPFM relies on the measurement and control of the electrostatic force between a conductive AFM cantilever and the investigated surface. Micro- and nanodroplets of glycerol were deposited on solid substrates (mica, graphite, silicon, silicon dioxide) and imaged via SPFM. The technique allowed the direct measurement of the contact angle and the study of its dependence on droplet size.

What is Scanning Polarization Force Microscopy?

SPFM is a **non-contact scanning probe technique** that offers the capability of measuring the **topography of liquid films or droplets** and **soft materials**. It relies on the **measurement of electrostatic interaction (polarization) forces** between a conductive AFM tip and the studied surface. As the electrostatic interaction has a longer range compared to the van der Waals interaction, the tip is able to follow the surface topography at a larger distance than in conventional AFM. SPFM can be used to study the wetting properties of liquids, the topography of biological materials etc.

The SPFM technique

Theory

Tip-surface system modeled as a **charged sphere in front of a dielectric surface** => an **image charge** appears inside the dielectric.

Tip charge:

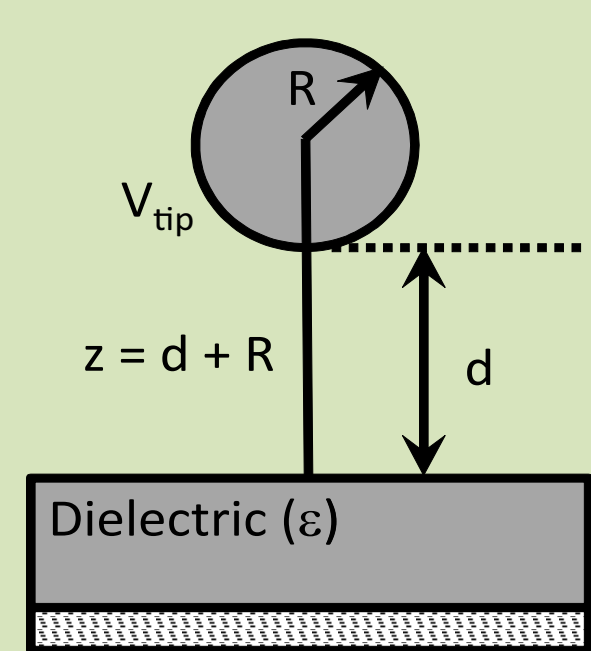
$$Q = 4\pi\epsilon_0 R V_{tip}$$

Image charge:

$$Q_i = \frac{\epsilon - 1}{\epsilon + 1} Q = -4\pi\epsilon_0 \frac{\epsilon - 1}{\epsilon + 1} R V_{tip}$$

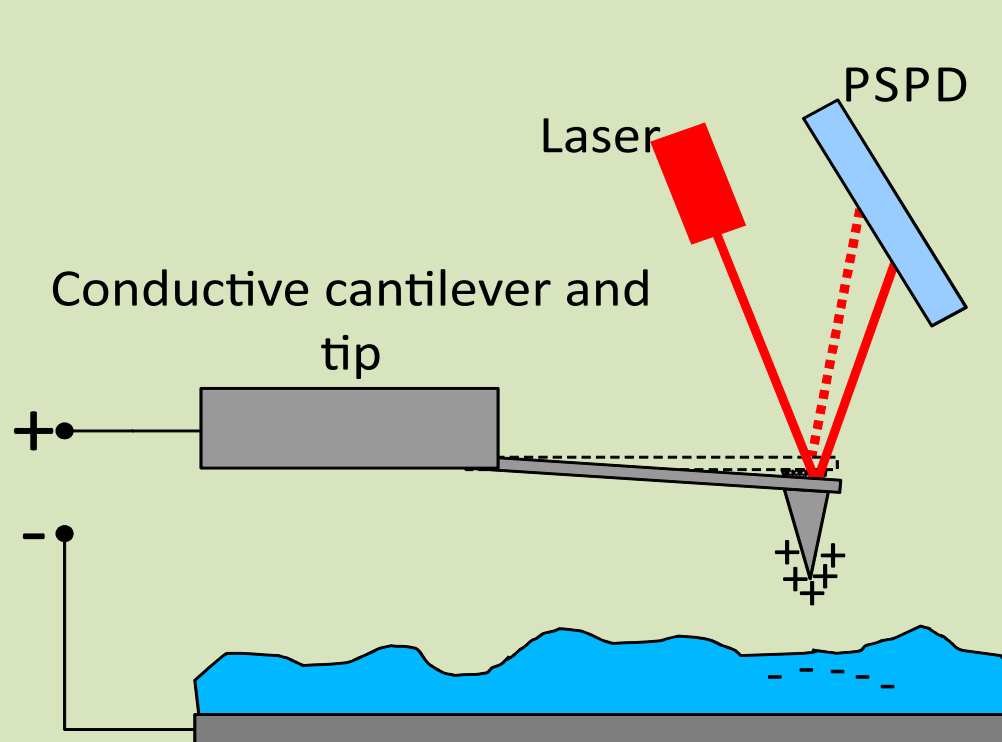
Electrostatic (polarization) force:

$$F = \frac{Q \cdot Q_i}{4\pi\epsilon_0 z^2} = -4\pi\epsilon_0 \frac{\epsilon - 1}{\epsilon + 1} \frac{R^2}{z^2} V_{tip}^2$$



SPFM-DC

- Tip located out of the range of the van der Waals forces => PSPD deflection is zero.
- When applying a **DC bias**, the **electrostatic force** (which will always be **attractive** due to the opposite signs of the charges) causes the cantilever to bend downwards => PSPD deflection becomes negative.
- The magnitude of the deflection also depends on tip-sample separation => by keeping the bending constant during scanning (via the topography feedback loop), one can actually follow the **surface topography in non-contact**.



SPFM-AC

Applied tip voltage:

$$V_{tip} \cdot \sin(\omega t) + V_{DC}$$

Existing local surface potential:

$$V_{surf}(x, y)$$

Resulting polarization force:

$$F = -4\pi\epsilon_0 \frac{\epsilon - 1}{\epsilon + 1} \frac{R^2}{z^2} (V_{tip} \cdot \sin(\omega t) - V_{surf}) = -4\pi\epsilon_0 \frac{\epsilon - 1}{\epsilon + 1} \frac{R^2}{z^2} \left[-\frac{1}{2} V_{tip}^2 \cdot \cos(2\omega t) + 2V_{tip} \cdot (V_{DC} - V_{surf}) \sin(\omega t) + \frac{1}{2} V_{tip}^2 + (V_{DC} - V_{surf}) \right]$$

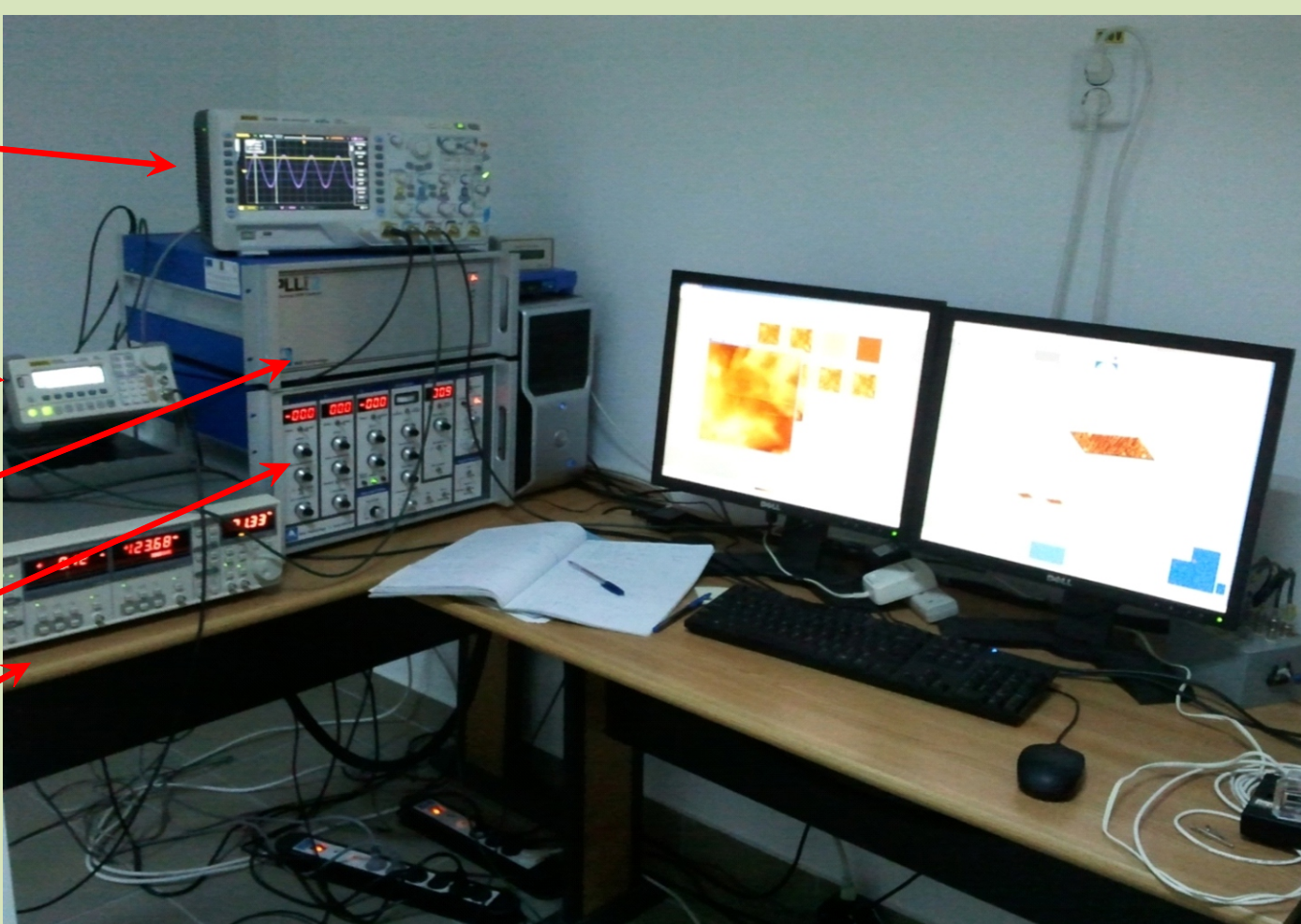
$$= F(2\omega) + F(1\omega) + F(0\omega)$$

The three components of F can be separated using a lock-in technique. $F(2\omega)$ is then used as an input for the topography feedback; while following the surface topography, the nulling of $F(1\omega)$, achieved when $V_{DC} = V_{surf}$, provides an (x, y) map of the local surface potential (Scanning Kelvin Probe Microscopy – SKPM).

SPFM implementation at CSSNT

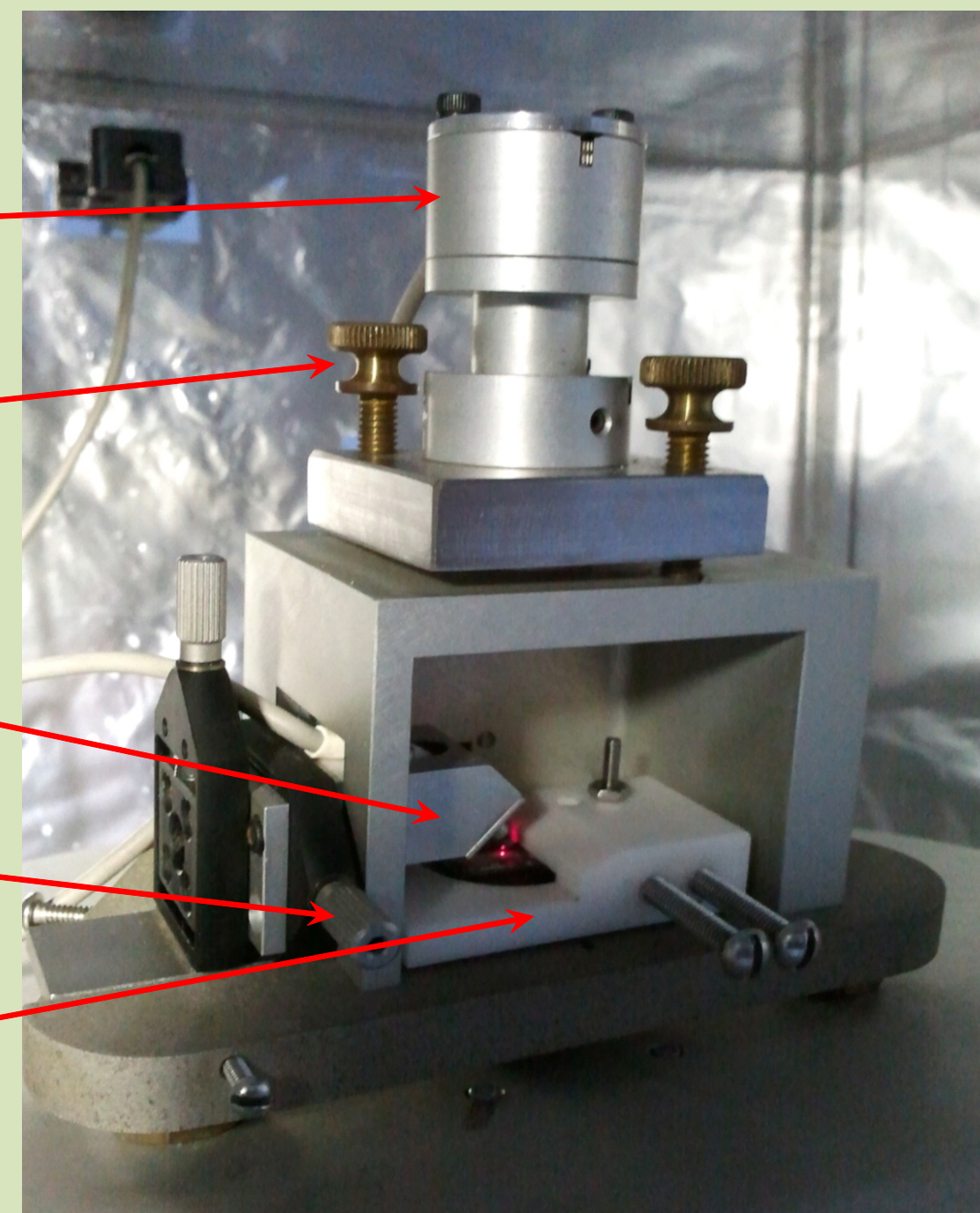
Electronics

1GHz, 4 channel Oscilloscope
Function generator
RHK PLLPro2
RHK SPM100
SRS830 lockin



AFM head

Laser diode
Laser adjustment knobs
PSPD
PSPD adjustment knobs
Chip holder

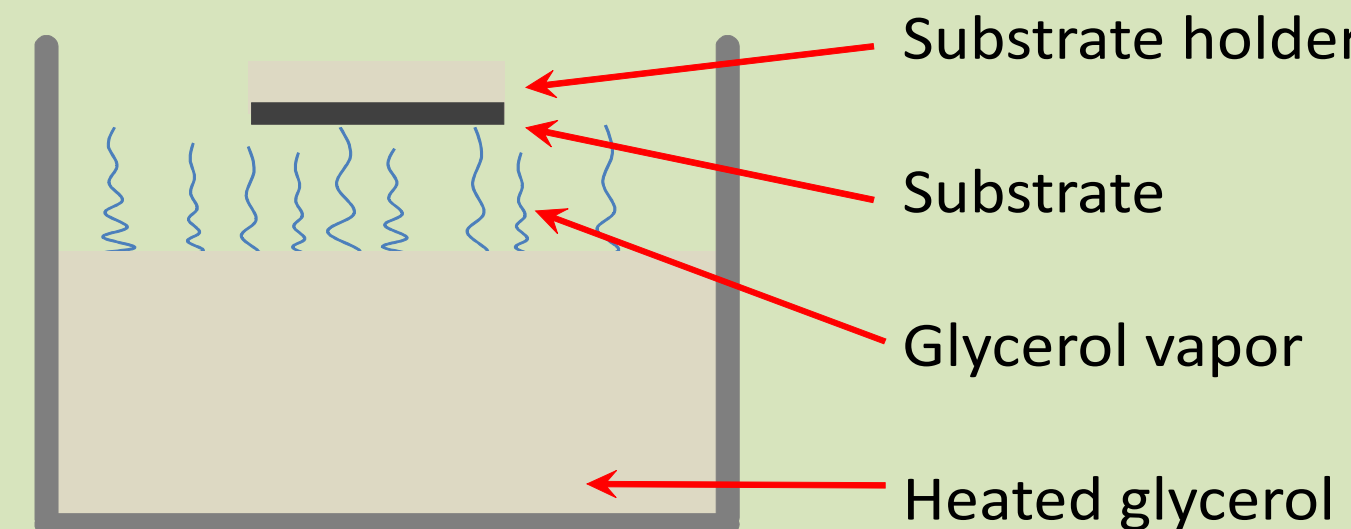


The AFM / SPFM laboratory of our Center was developed around a home-built advanced SPM system, which is currently driven by a state-of-the-art controller and is capable of: “classical” AFM (contact, non-contact, intermittent contact), STM, MFM, I-AFM (current AFM), SPFM and much more.

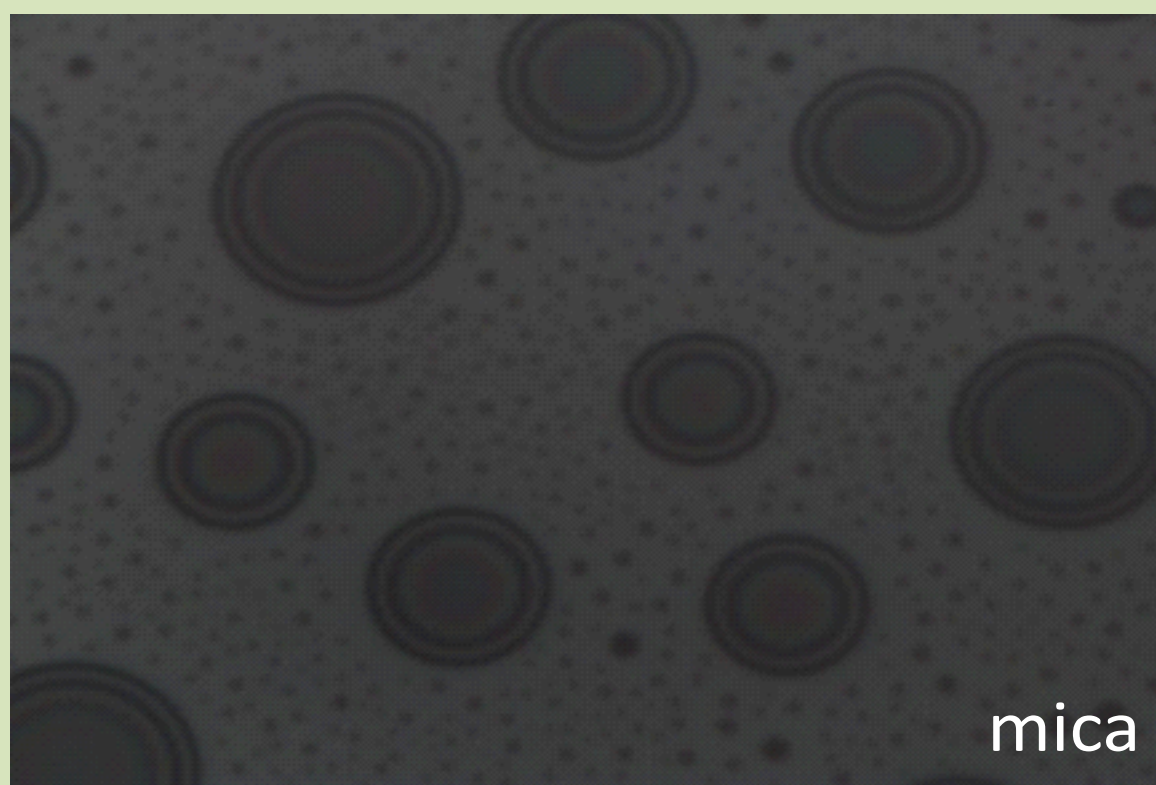
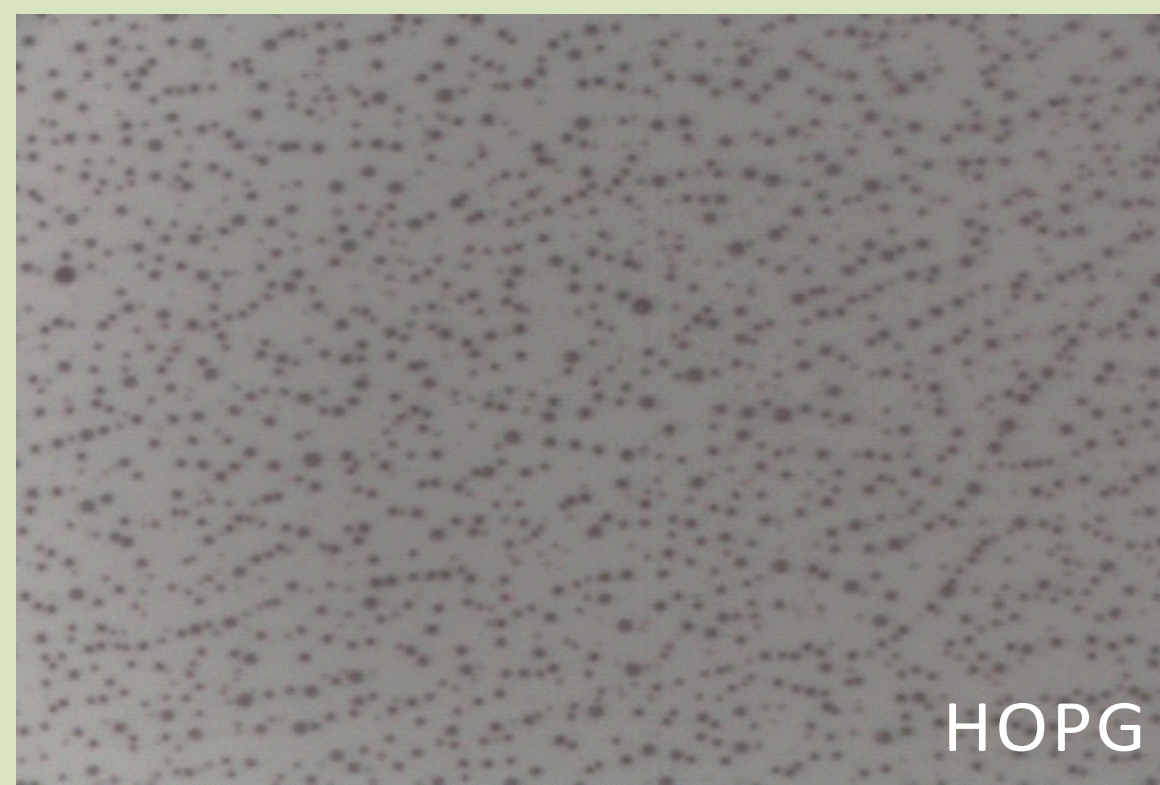
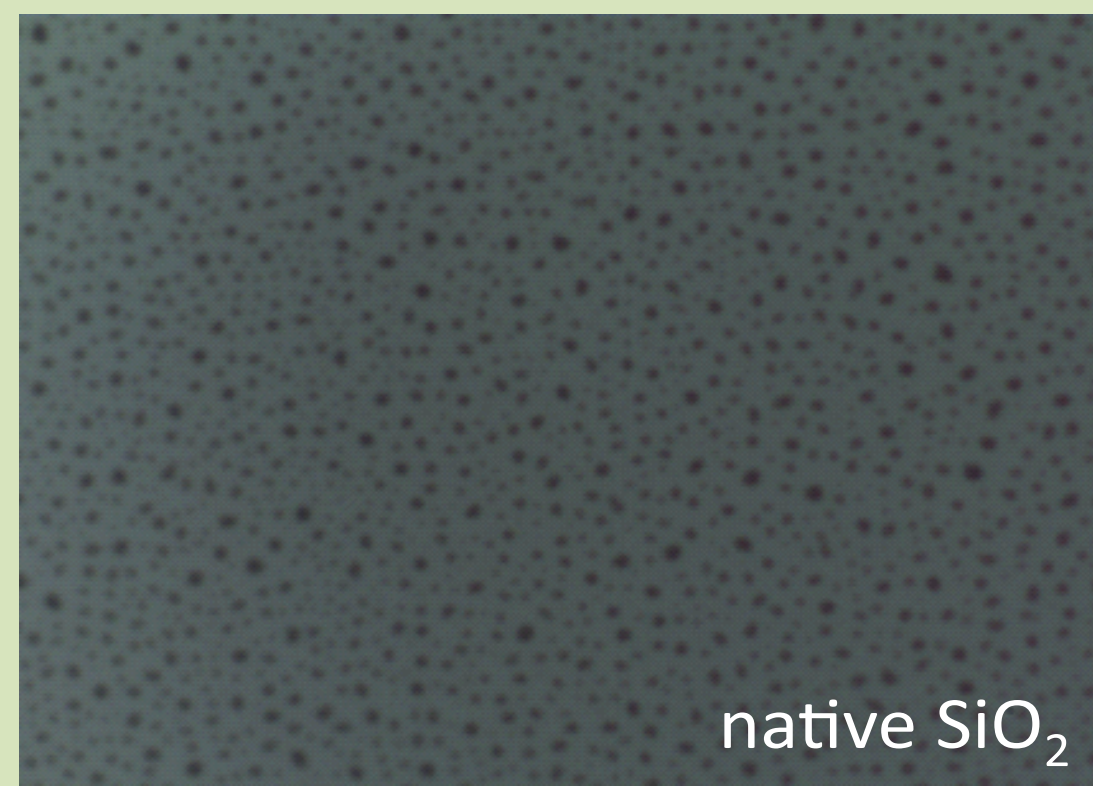
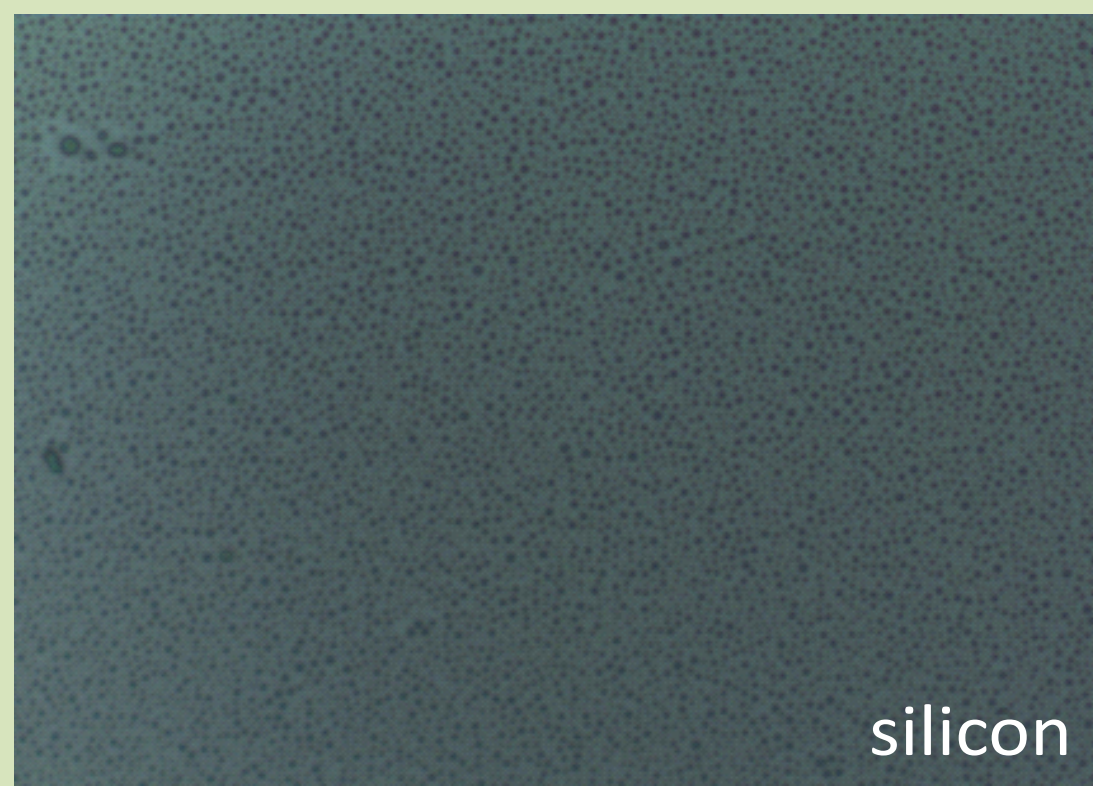
Study of the wetting properties of liquids

Deposition of glycerol micro- and nanodroplets

Glycerol droplets were created on the substrates by condensation: the substrates were held upside down inside a Berzelius glass containing heated glycerol, at a height of ~5 mm above the liquid surface. After a few seconds the surface of the substrates achieved a “foggy” appearance, which proved the presence of microscopic droplets.

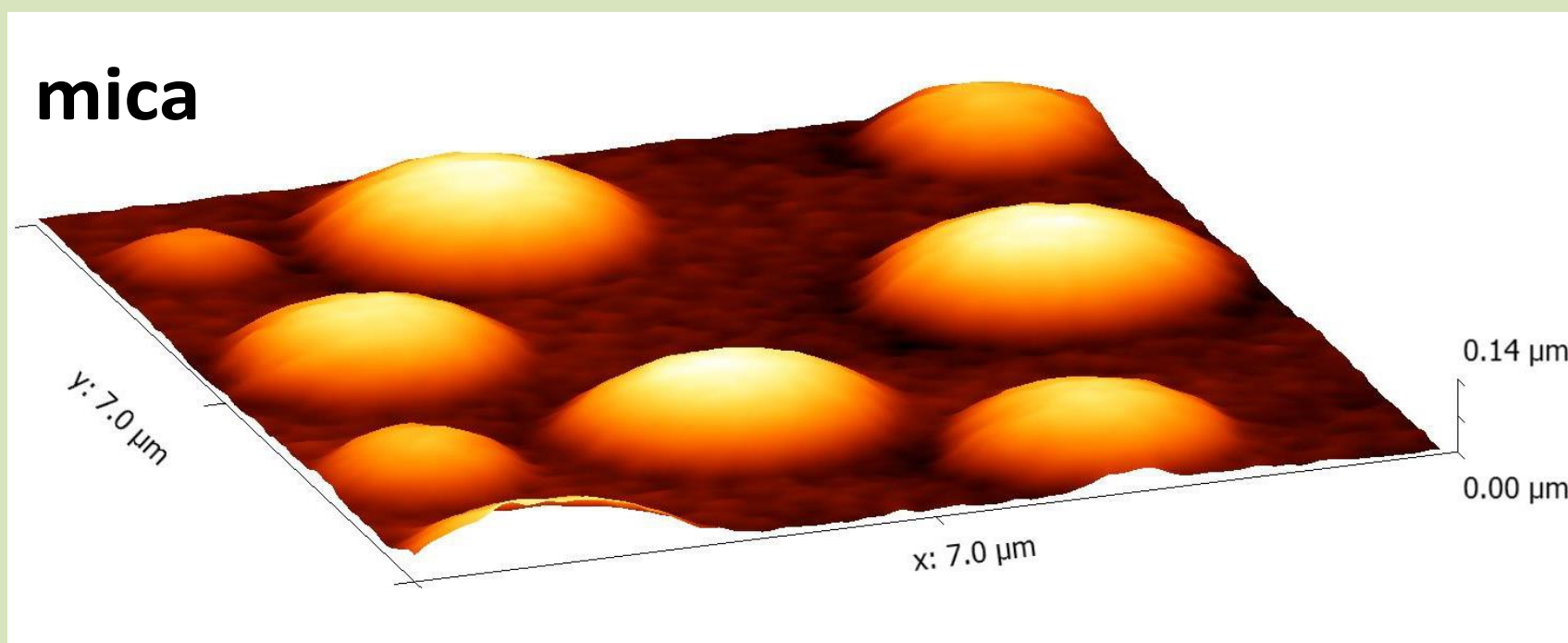
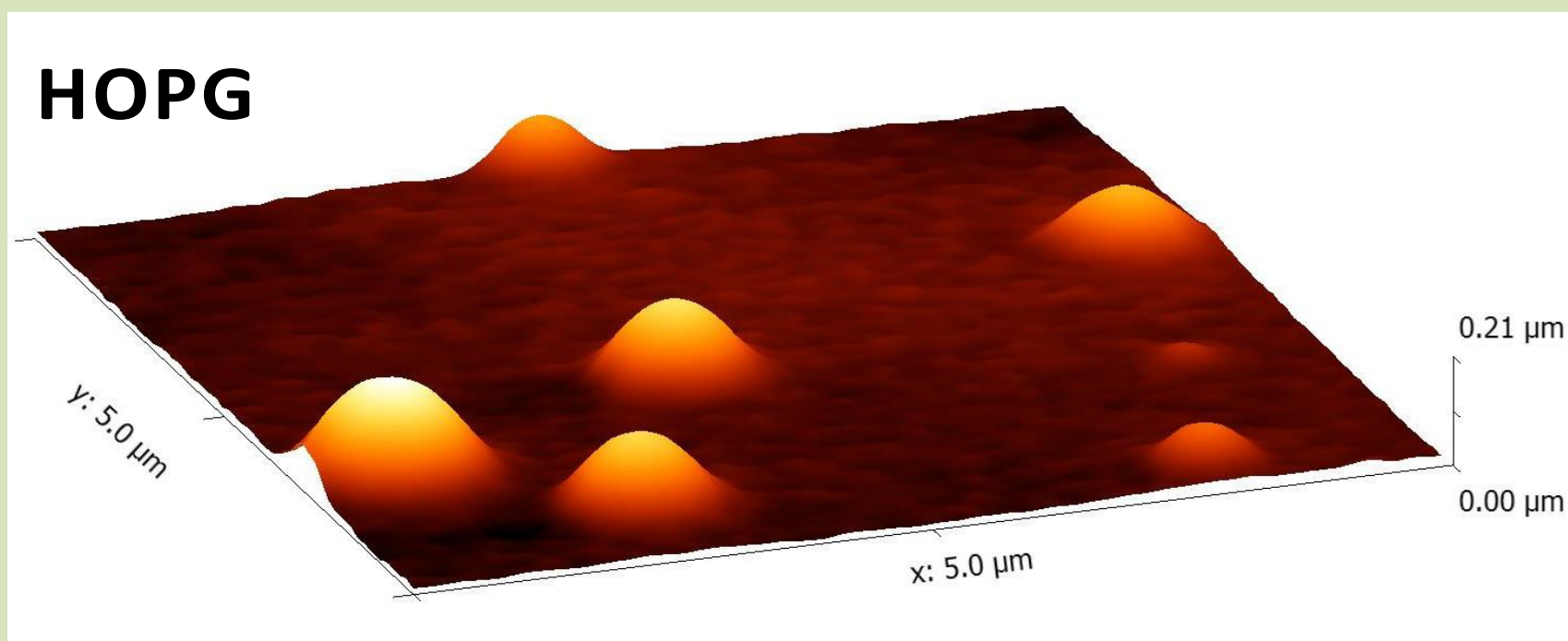
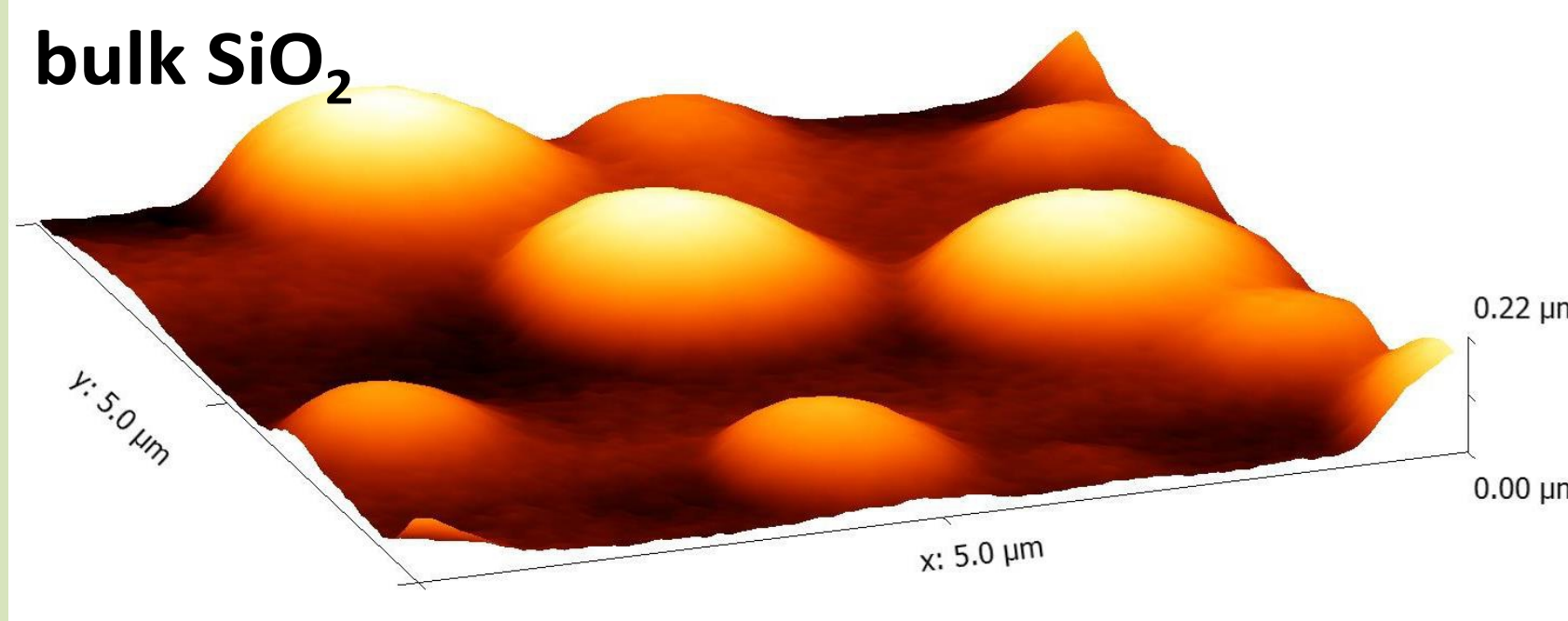
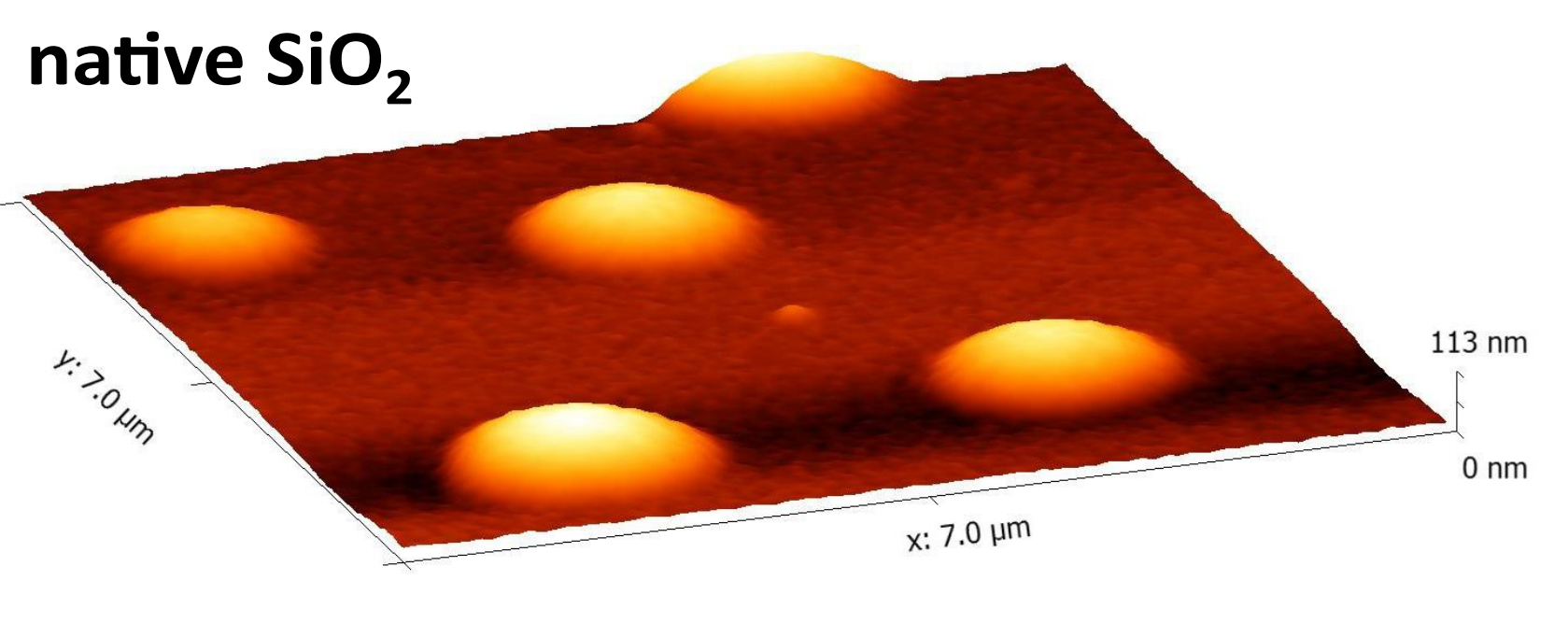
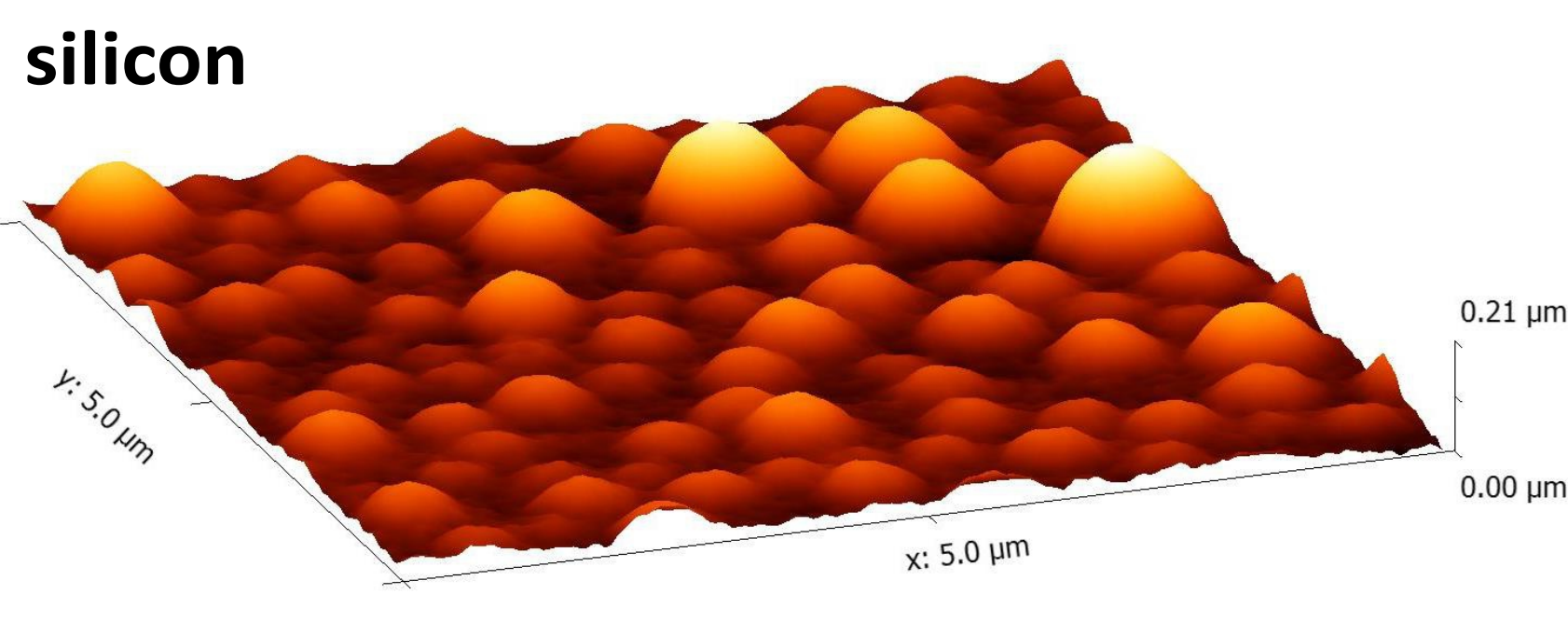


Optical analysis of deposited glycerol droplets



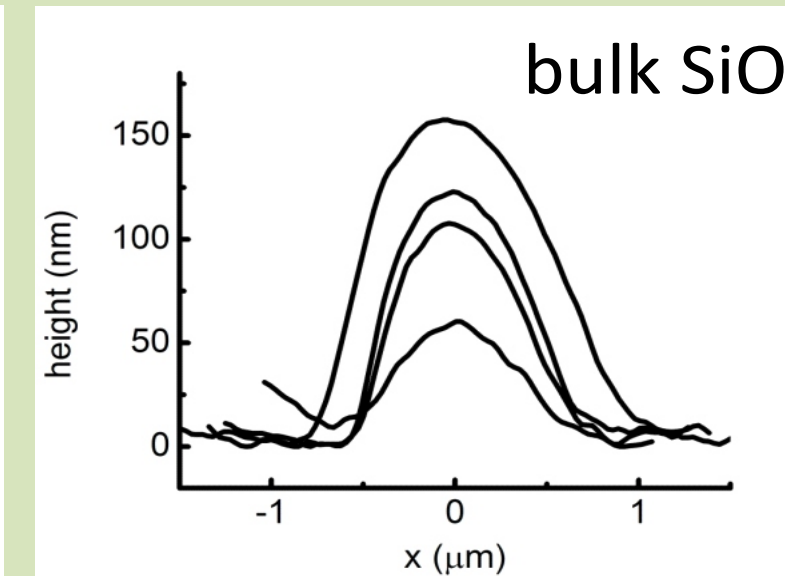
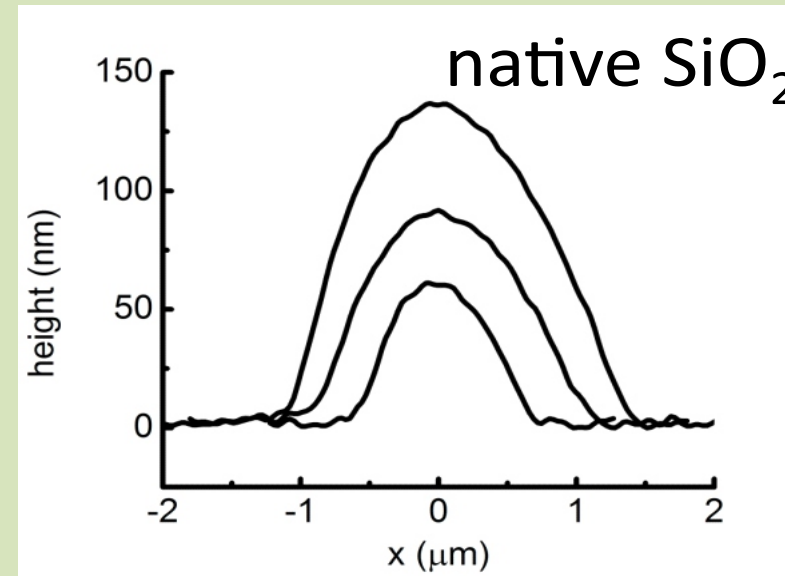
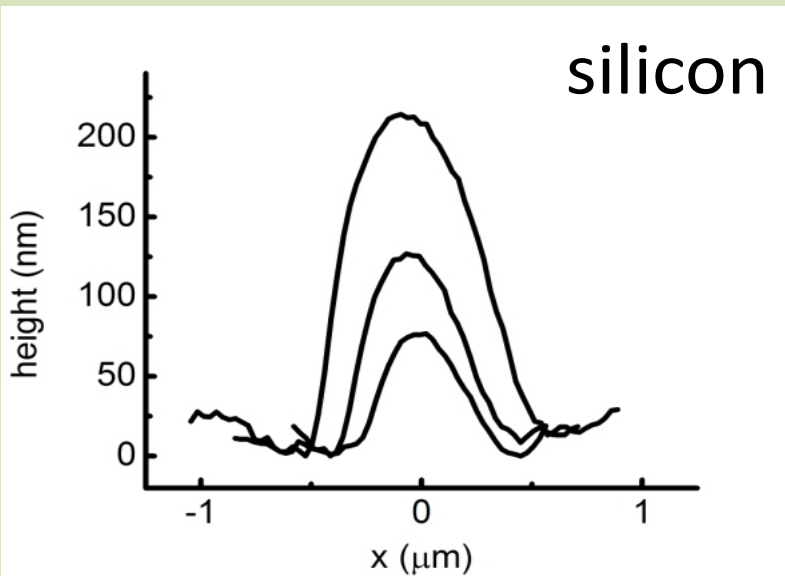
Field of view
~70µm × 55µm
for all images

Visualising glycerol micro- and nanodroplets by SPFM

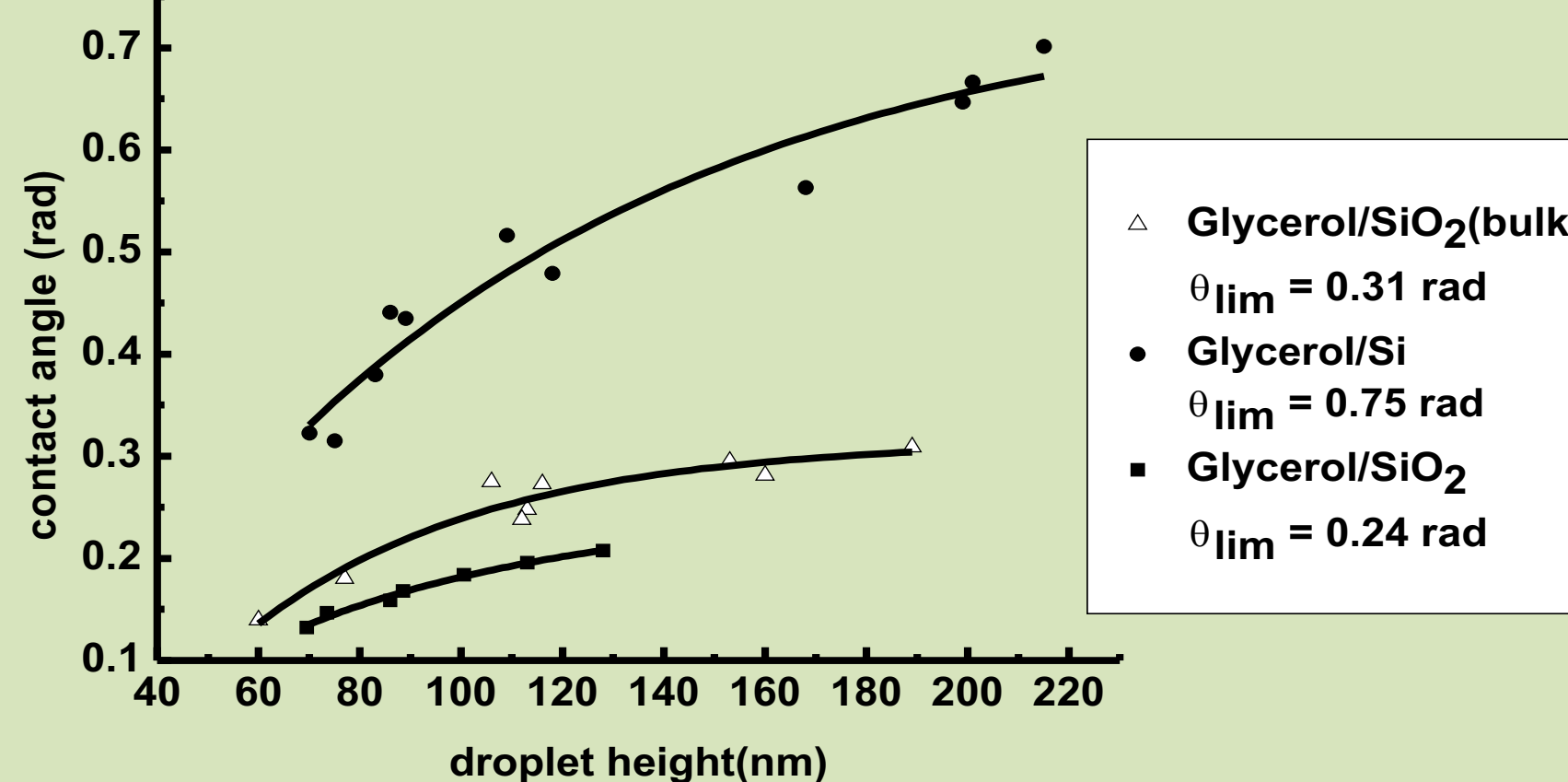


Line-cut profiles of the droplets

Extracted from the SPFM topography images for Si, native SiO2 and bulk SiO2

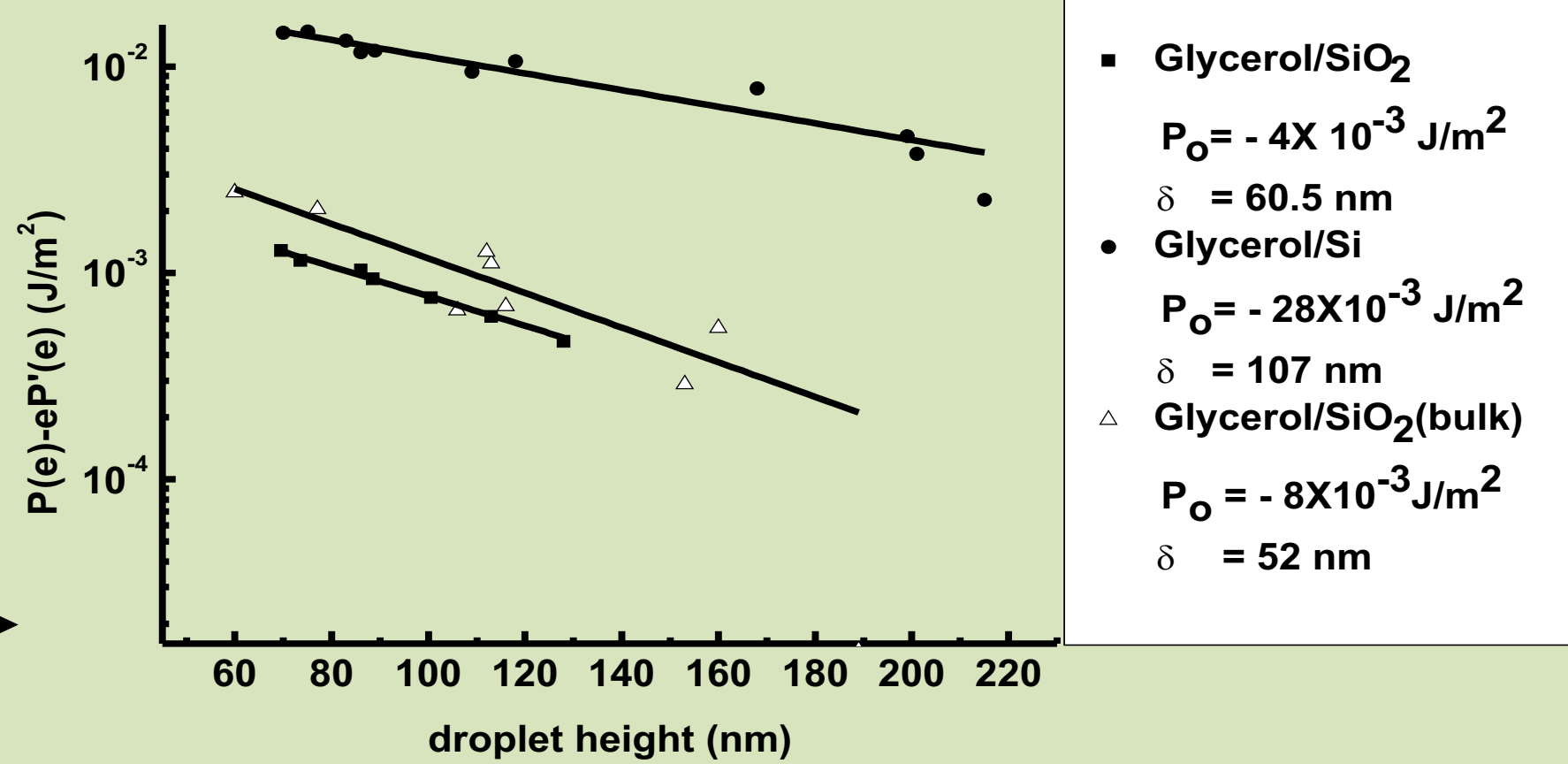


Direct calculation of the microscopic contact angle θ and determination of its dependence on droplet height



Contact angle dependence on droplet height allowed the determination of the **potential energy** dependence on droplet height using

$$\theta^2 = \theta_0^2 + \frac{2}{\gamma} [P(e) + eP'(e)] \Rightarrow P(e) - eP'(e) = (\theta^2 - \theta_0^2) \frac{\gamma}{2}$$



$$P(e) = -28 \cdot 10^{-3} \exp(-e/107 \text{ nm}) \text{ J/m}^2 \text{ for glycerol on Silica}$$

$$P(e) = -4 \cdot 10^{-3} \exp(-e/60.5 \text{ nm}) \text{ J/m}^2 \text{ for glycerol on native SiO}_2$$

$$P(e) = -8 \cdot 10^{-3} \exp(-e/52 \text{ nm}) \text{ J/m}^2 \text{ for glycerol on bulk SiO}_2$$

ACKNOWLEDGMENTS

This work was supported by the Romanian Ministry of Education, Research, Youth and Sport; by the European Union through the European Regional Development Fund; by the Romanian National Authority for Scientific Research, under project POSCCE-O 2.1.2-2009-2/12689/717.